# Accelerating meta-atom design with optimization, inverse design and Al methods: an application oriented benchmark

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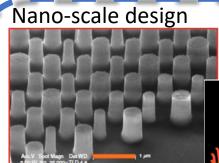
14th International Photonics and OptoElectronics Meeting,

Wuhan China

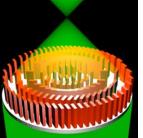


# PlanOpSim

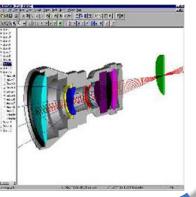




Component design



**System Integration** 



Planopsim's mission

Planopsim supplies R&D tools to engineers & scientists that allow to unlock the maximum benefit of flat optics in a user-friendly way.



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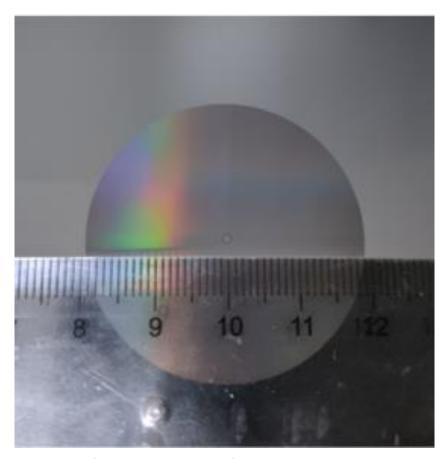
# Bottlenecks in meta-surface design



- Nano-structure full wave solution
  - > All full wave algorithms scale poorly vs. DOF
  - > Calculation times run into days to weeks easily
- Large area:
  - > Memory limitations
  - > Multi-scale methods increase the limit but require approximation
- Integration to system level
  - > Link from wave to ray scale not well developed
  - > Current models ignore higher order diffraction and amplitude

Example on-demand estimate for production (USD):\*

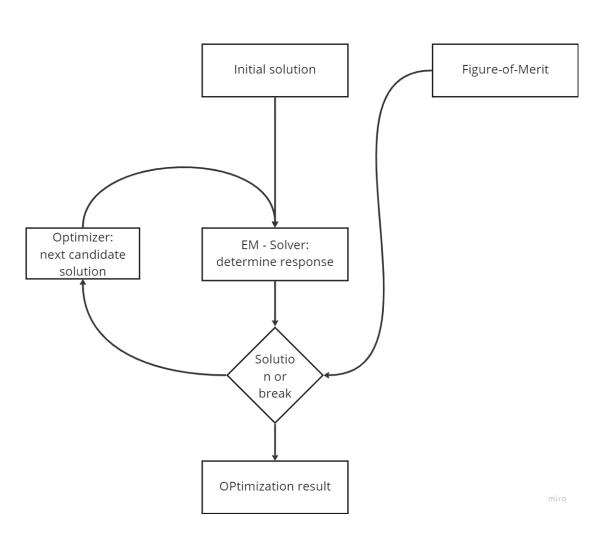
- License server (t3.nano, 10 GB storage): \$5/month
- Compute instances (4 x c5n.18xlarge, 20 GB storage each): \$11,360/month, \$16/hour
- Shared storage (EFS, 1 TB usage): \$300/month



40mm diameter metalens

# Speeding up nano-structure search



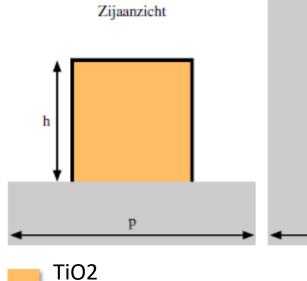


- Most time consuming aspect of design is the simulation of nano-structures
  - > Typical: several **10 000s of structures**
  - > Parametrized structures
  - > Arbitrary shape structures
- Design contains a solver and an optimization loop
  - > Time spent = #calls x loop time
  - > Loop time determined by EM solver
- Two approaches to speed up:
  - > Reduce #calls: smartest optimization alogrithm
  - > Reduce loop time: fastes solver
- "Orthogonal" approaches can be combined

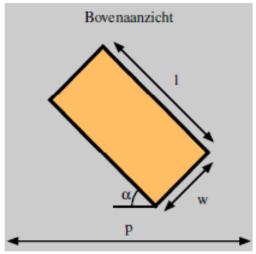
Ampbell, S. A. D. C., Ell, D. A. S., Enkins, R. O. P. J., Ric, E. B., Hiting, W., An, J. O. A. F., & Erner, D. O. H. W. (2019). Review of numerical optimization techniques for meta-device design. *Optical Materials Express*, 9(4), 1842–1863.

# Reference problem





BK7



## \* Reference problems:

> Optimization of Pancharatnam Berry phase structures

## Standard design approach

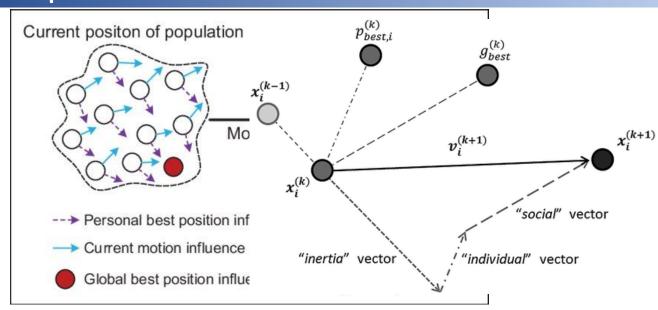
- ➤ Library of 32 structures
- > Fixed height and unit cell
- ➤ TiO2 on glass
- > Wavelength 633nm
- > Period: 430nm

#### Benchmark:

- > Brute force parameter sweep
- > Particle Swarm Optimization
- ➤ Genetic Algorithm
- > Differential evolution
- > Covariance Matrix Adaptation Evolution Strategy
- > Bayesian optimization

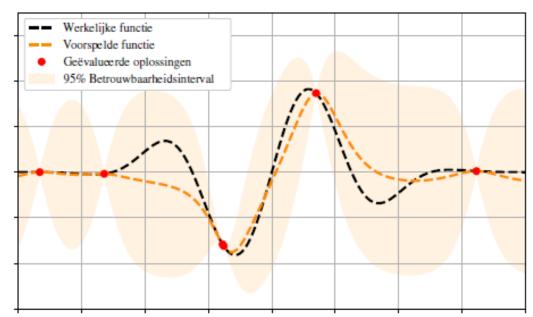
# Optimization: methods





## Particle swarm optimization (PSO)

- Multiple starting points
- Direction of particle controlled by:
  - > Best solution of all particles
  - > Best position of individual particle
  - > Momentum of individual particle

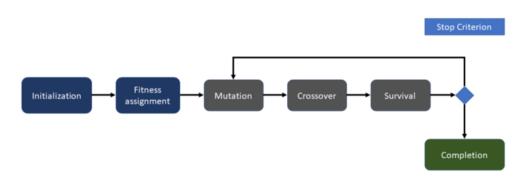


## **Bayesian Optimization**

- Constructs a polynomial approximation of the error landscape from previous iterations
- Analytical solution of appriximate polynomial error landscape

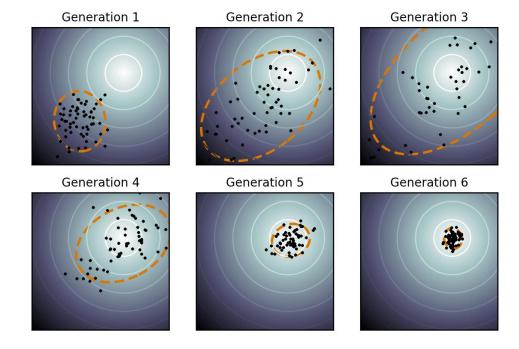
# Optimization: methods





## Genetic algorithm (GA) and Differential evolution (DE)

- Multiple starting points (population)
- Evolution over multiple iterations
  - > Best solutions kept
  - > Best solutions are changed by :
    - Cross-over
    - Random mutation



# **Covariance Matrix Adaptation Evolution Strategy** (CMAES)

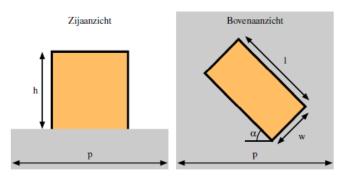
- Sampled solutiuons via normal distribution
- Evolution over multiple iterations
  - > Best solutions kept
  - > Search area expanded/decreased based on rate of change

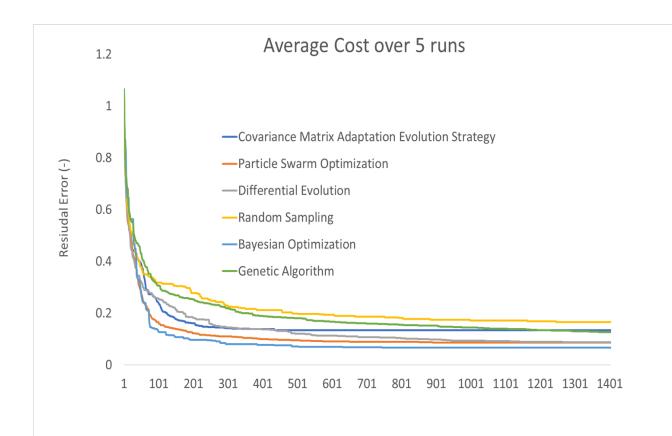
# Benchmark results



- Pancharatnam Berry structure optimization
- Convergence reached in 400-1500 solver calls
- **\Leftrightarrow** Error defined as  $\varepsilon = |t t_{target}|$

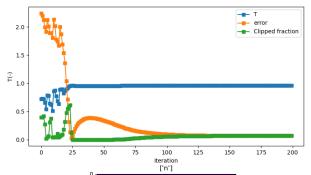
| Algorithm | Final error | #calls to converge |
|-----------|-------------|--------------------|
| Bayes     | 0,066       | 485                |
| PSO       | 0,086       | 509                |
| DE        | 0,0878      | 917                |
| GA        | 0,126       | 1123               |
| CMAES     | 0,133       | 245                |

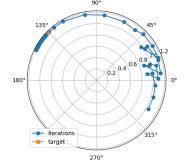


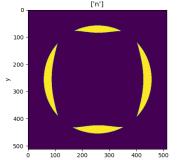


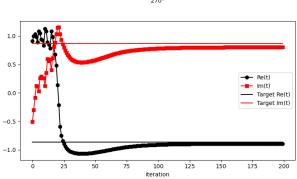
# Adjoint optimization









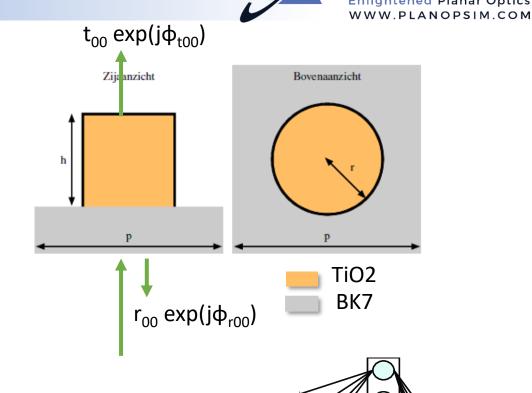


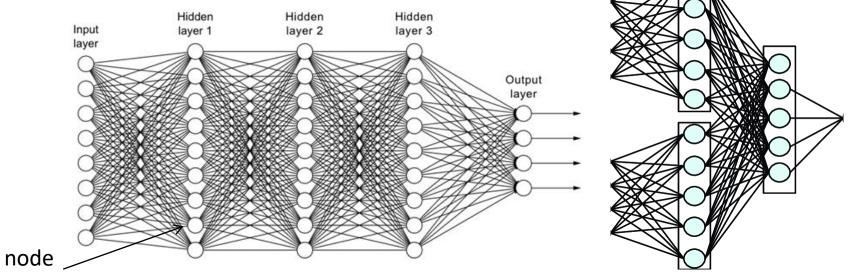
| Algorithm            | Final error | #calls to converge |
|----------------------|-------------|--------------------|
| Adjoint Optimization | 0,05        | 200                |
| Bayes                | 0,066       | 485                |
| PSO                  | 0,086       | 509                |
| DE                   | 0,0878      | 917                |
| GA                   | 0,126       | 1123               |
| CMAES                | 0,133       | 245                |

- Adjoint optimization
  - > 2 solver calls per optimization
  - > Gradient descent optimization
- Needs post-processing for:
  - > Binary material distribution
  - > Realistic feature sizes
- Post processing limits convergence and final result

# Surrogate solver

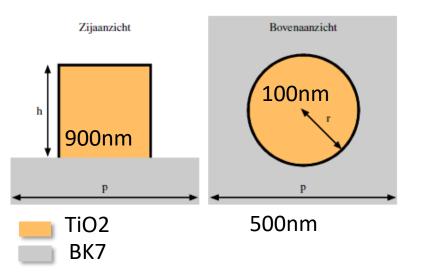
- ❖ Neural networks trained to predict RCWA solver answers
  - > Reflected and transmitted phase and amplitude
  - > Fundamental order (00)
- Physical parameters
  - Period P
  - > Height H
  - > Radius r
  - > TE/TM
  - > \(\lambda\): 450-700nm





# Surrogate NN results: example result

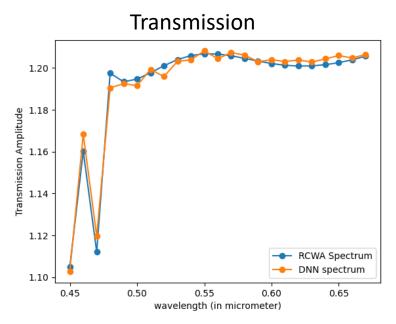


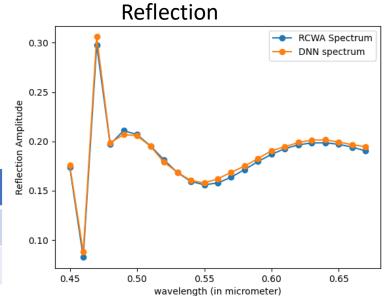


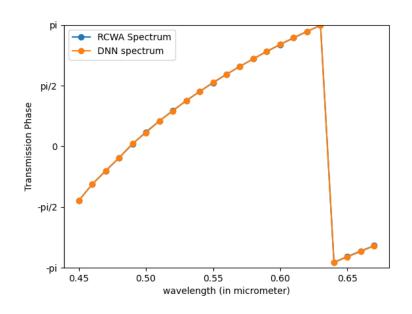
- DNN reproduces transmission and reflection
- Amplitude and phase reproduced
- Error metric: Euclidian distance

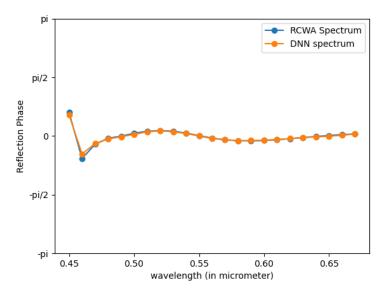
$$SE_{r/t} = |r/t_{NN} - r/t_{RCWA}|^2$$

| Direction    | MSE      | Mean Error |
|--------------|----------|------------|
| Transmission | 7,2 10-5 | 0,85%      |
| Reflection   | 5,6 10-5 | 0,75%      |



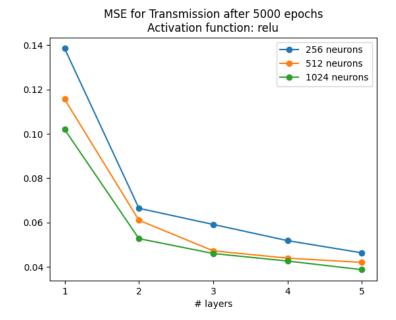


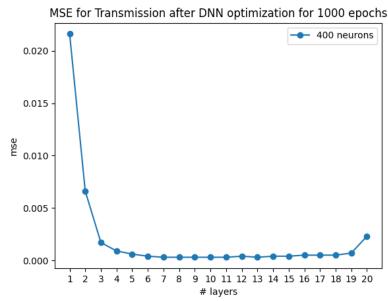




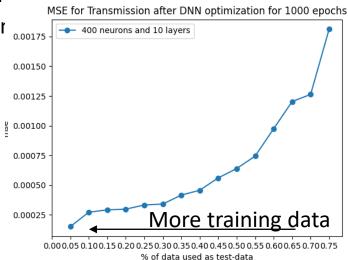
## Effect of network choice





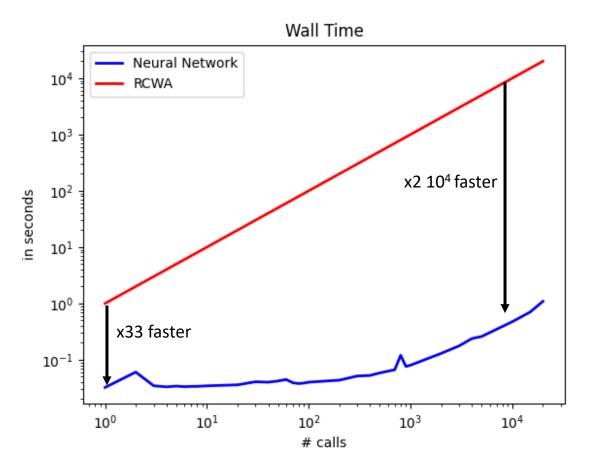


- Sufficient network complexity needed
  - > Layers
  - > Neurons per layer
- ❖ Neural Network types:
  - > Fully connected layers
  - > Shared layer network
  - Neural tensor layer
  - #nodes and # layers optimized
- Training data:
  - ➤ Large amount: 14
  - > Representative sar



# But is it faster?



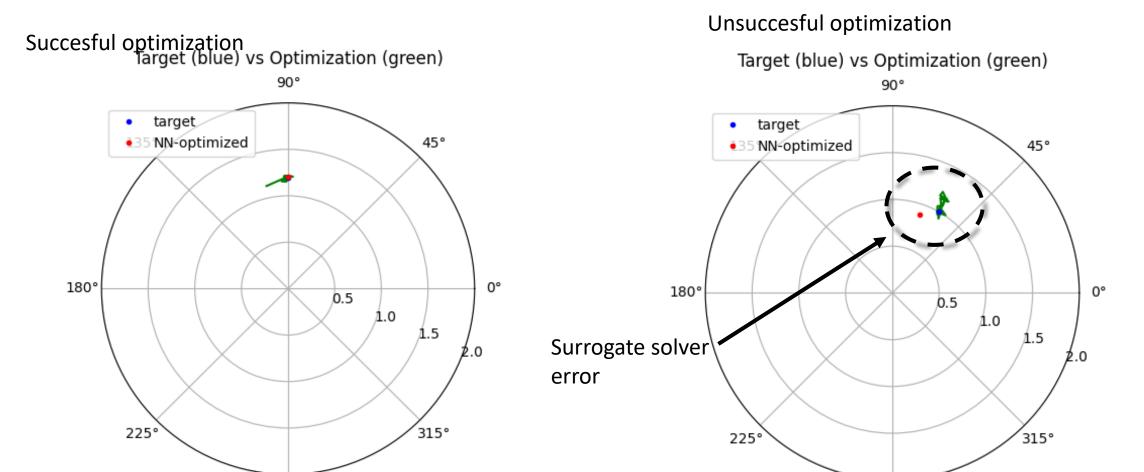


- ❖ Surrogate NN is 33 20 000 times faster than direct RCWA call
- ❖ 1 call (0,033s) 33x faster
- ◆ 9000 parallel calls (0,44s) -> 20 000 times faster

# Surrogate solver + optimization



- Seacrh via genetic algorithm combined with surrogate solver
- Direct implementation: 31sec
- Optimized for large batches: 4,5sec



# Conclusions



- ❖ Surrogate solver and optimization methods can be used to speed up meta-atom design up to 500 fold
- ❖ PSO, Bayesian and adjoint method are most performant optimization algorithms
- Surrogate needs a pre-trained and accurate network. Training takes more time than a classical design.
- Surrogate only applicable to pre-defined material platform (substrate + material)

|                         | #solver calls | Time per call | Total calculation time | Acceleration factor |
|-------------------------|---------------|---------------|------------------------|---------------------|
| Brute force sweep       | 64 000        | 1.1s          | 19.55hr                | 1 (baseline)        |
| Parameter optimization  | 32 000        | 1.1s          | 8.9hrs                 | 2                   |
| (Bayesian)              |               |               |                        |                     |
| Neural network training | 400 000       | 1.1s          | 122hrs                 | 0.16                |
| Brute force pre-trained | 64 000        | 0.03s         | 0.53hrs                | 37                  |
| surrogate               |               |               |                        |                     |
| Genetic + pre-trained   | 32 000        | 0.03s         | 0.27hrs                | 72                  |
| surrogate               |               |               |                        |                     |
| Brute force pre-trained | 32 000        | 0,005s        | 0,04hrs (3mins)        | 488                 |
| surrogate               |               |               |                        |                     |

## Contact info



## Reach us here!



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